

# Using Graph Properties for Global Constraints for Necessary Conditions and Filtering

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Using Graph  
Properties for Global  
Constraints for  
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The Framework

Example: nvalue

Graph Invariants

Bounds On Graph Char

Towards Graph-Based F

Conclusion

March 14, 2006



# Outline

## The Framework

**Example:** `nvalue`

## Graph Invariants

## Bounds On Graph Characteristics

## Towards Graph-Based Filtering

## Conclusion

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# Context and Key Ideas

- ▶ Global Constraints as **Graph Properties** of **Structured Networks** of **Elementary Constraints** of the **Same Type** [BelCarRam05].
- ▶ Graph Properties are **not independent**. They are related by Graph Invariants.
- ▶ Graph Invariants are **generic**. Some 150 of them have been collected in a database.
- ▶ Given a constraint  $C$  specified in terms of Graph Properties, the relevant Graph Invariants form **necessary conditions** for  $C$ .
- ▶ Bounds on Graph Characteristics can be computed dynamically and be used for **pruning**.

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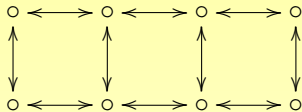
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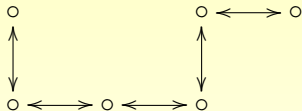
# A Simple Global Constraint

## Initial network



Arcs are associated with elementary constraints.

## Final network



Ask properties of sub-graph of elementary constraints that still hold.

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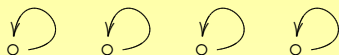
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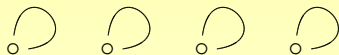


# Graph Generators

## LOOP



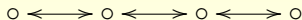
## SELF



## PATH



## CHAIN



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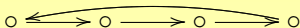
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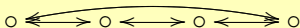


# Graph Generators

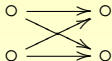
## CIRCUIT



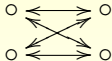
## CYCLE



## PRODUCT



## SYMMETRIC PRODUCT



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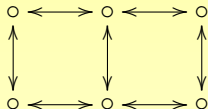
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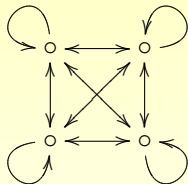


# Graph Generators

## GRID



## CLIQUE



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# Graph Characteristics

NVERTEX  $|V(G)|$

NEDGE  $|E(G)|$

NSOURCE number of vertices without predecessor

NSINK number of vertices without successor

NCC number of connected components of  $G$

MIN\_NCC number of vertices of smallest c.c. of  $G$

MAX\_NCC number of vertices of largest c.c. of  $G$

NSCC number of strongly connected components of  $G$

MIN\_NSCC number of vertices of smallest s.c.c. of  $G$

MAX\_NSCC number of vertices of largest s.c.c. of  $G$

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# Graph Properties and Graph Invariants

- ▶ A **graph property** is a relation  $C \circ V, \circ \in \{\leq, \geq, =, \neq\}$ , where  $C$  is a graph characteristic and  $V$  is a domain variable.
- ▶ A **graph invariant** is a relation on graph characteristics that is valid for a graph class.
- ▶ Example:

$$\begin{aligned} \text{MIN\_NSCC} &\neq \text{MAX\_NSCC} \\ &\Rightarrow \\ \text{NVERTEX} &\geq \text{MIN\_NSCC} + \text{MAX\_NSCC} \end{aligned}$$

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# nvalue(*NVAL*, *VARS*)

arguments *NVAL* : dvar, *VARS* : collection(var – dvar)

restrictions  $0 \leq NVAL \leq |VARS|$

arc input variables

arc generator clique

arc constraint  $VARS.var[1] = VARS.var[2]$

graph properties  $NSCC = NVAL$

example  $nvalue(3, \{var - 3, var - 1, var - 7, var - 1\})$

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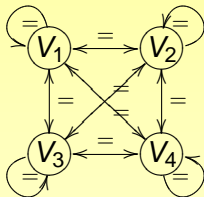
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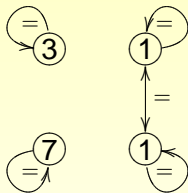


$nvalue(3, \{var - 3, var - 1, var - 7, var - 1\})$

Initial network: variables unbound



Final network: variables instantiated, NSCC = 3



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# Graph Invariants for $nvalue$

A lower bound on  $NVAL$  in  $nvalue(NVAL, VARS)$ :

$$NSCC \geq \left\lceil \frac{NVERTEX^2}{NARC} \right\rceil$$

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# Tighter Graph Invariants

- ▶ Typically, the graph for a global constraint has a specific structure. The arc generator and arc constraint determine the **graph class**.
- ▶ A general graph invariant:

$$\text{NARC} \leq \text{NVERTEX}^2$$

- ▶ A tighter graph invariant that holds for graph class PATH:

$$\text{NARC} \leq \text{NVERTEX} - 1$$

- ▶ Other invariants are specific e.g. for acyclic, bipartite, or symmetric graphs.

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# A Database of Graph Invariants

Queried by: a set of graph characteristics (GCs) and a graph class, determined by the constraint of interest.

Statistics:

#graphs	#GC	#invariants
1	1	13
1	2	50
1	3	34
1	4	12
1	5	2
2	2	10
2	3	10
2	4	6
2	5	16
2	6	4

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# Bounds on Graph Characteristics

- ▶ Results to date on general graphs are shown in the table.
- ▶ **Tighter** and **cheaper** bounds can be found for specific graph classes.

G.C.	Sharp	Complexity	Bound
<u>NARC</u>	yes	P	$ E_T  +  X_{T, \neg T}  - \mu(\vec{G}(X_{T, \neg T}, E_U))$
<u>NARC</u>	yes	P	$ E_{TU} $
<u>NVERTEX</u>	yes	NP	$ X_T  + h(\vec{G}((X_{T, \neg T, \neg T}, X_{U, \neg T, T}), E_{U, T}))$
<u>NVERTEX</u>	yes	P	$ X_{TU} $
<u>NCC</u>	yes	P	$cc_{[ X_T  \geq 1]}(\vec{G}(X_{TU}, E_{TU}))$
<u>NCC</u>	yes	P	$cc_{[ E_T  \geq 1]}(\vec{G}(X_T, E_T)) + \mu_l(\vec{G}_{rem})$
<u>NSCC</u>	yes	NP	$scc_{[ X_T  \geq 1]}(\vec{G}(X_{TU}, E_{TU})) + h(G_{\underline{NSCC}}((Y, Z), E))$
<u>NSCC</u>	yes	P	$scc(\vec{G}(X_{TU}, E_T))$
<u>NSINK</u>	yes	NP	$sink_{[ X_T =1]}(\vec{G}(X_{TU}, E_{TU})) + h(G'_r((Y, Z), E))$
<u>NSINK</u>	no	P	$sink(\vec{G}(X_T, E_T)) +  X_U  -  source_{[ X_U =1]}(\vec{G}(X_{TU}, E_{TU}))  -  XP $

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# Filtering: definitions

Given a constraint  $C(v_1, \dots, v_n, x_1, \dots, x_m)$  with associated digraph  $\mathcal{G} = (\mathcal{X}, \mathcal{E})$ , binary arc constraint  $ctr$ , graph characteristics  $\Xi_1, \dots, \Xi_n$ , and variables:

- ▶ A 0/1 variable  $z_j$  for each vertex  $j \in \mathcal{X}$ .
- ▶ A 0/1 variable  $z_{jk}$  for each arc  $(j, k) \in \mathcal{E}$ .

$C$  is equivalent to the following system of constraints:

$$z_{jk} = 1 \Leftrightarrow ctr(x_j, x_k), (j, k) \in \mathcal{E} \quad (1)$$

$$z_j = \bigvee_{\{k | (j,k) \in \mathcal{E} \vee (k,j) \in \mathcal{E}\}} z_{jk}, j \in \mathcal{X} \quad (2)$$

$$c_i = \Xi_i(\{z_j \mid j \in \mathcal{X}\}, \{z_{jk} \mid (j, k) \in \mathcal{E}\}), 1 \leq i \leq n \quad (3)$$

$$c_i \circ_i v_i, 1 \leq i \leq n \quad (4)$$



# Graph-Based Filtering: a first attempt

- ▶ Given a constraint  $C(v_1, \dots, v_n, x_1, \dots, x_m)$ , filtering can be obtained by posting constraints (1,2,3,4).
- ▶ Constraints (3) need propagators:

---

**PROCEDURE**  $\Xi(\{z_j \mid j \in \mathcal{X}\}, \{z_{jk} \mid (j, k) \in \mathcal{E}\}, c)$

- 1: Evaluate  $\underline{c}'$  and  $\overline{c}'$  wrt.  $(\{z_j\}, \{z_{jk}\})$
  - 2:  $\min(c) \leftarrow \max(\underline{c}', \min(c))$
  - 3:  $\max(c) \leftarrow \min(\overline{c}', \max(c))$
  - 4: **if**  $\min(c) = \max(c) = \overline{c}'$  **then**
  - 5:     Fix some  $z_j, z_{jk}$  in order to avoid  $c' < \overline{c}'$
  - 6: **if**  $\min(c) = \max(c) = \underline{c}'$  **then**
  - 7:     Fix some  $z_j, z_{jk}$  in order to avoid  $c' > \underline{c}'$
- 

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# group01 — a PATH+LOOP Constraint

*group01*(*NGroup*, *MinSize*, *MaxSize*, *MinDist*, *MaxDist*, *NOne*, *VARS*) holds if:

- ▶ *VARS* is a sequence of 0/1-variables
- ▶ an *i*-group is a maximal sequence of values *i*
- ▶ *VARS* contains *NGroup* 1-groups
- ▶ *MinSize* (*MaxSize*) is the length of the smallest (largest) 1-group
- ▶ *MinDist* (*MaxDist*) is the length of the smallest (largest) 0-group
- ▶ *NOne* is the total number of 1s

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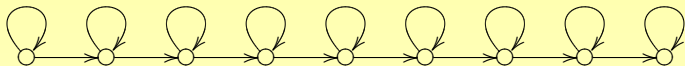
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# group01 — Graph Properties

group01(2, 2, 4, 1, 2, 6, {0, 0, 1, 1, 0, 1, 1, 1, 1})

**Initial network: variables unbound**



**Final network: ones**



**Final network: zeros**



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## group01 — Filtering

group01(*NGroup*, *MinSize*, *MaxSize*, *MinDist*, *MaxDist*, *NOne*, *VARs*) with  $m$  0/1-variables is equivalent to:

$$z_j = (VARs_j \wedge VARs_{j+1}), \quad 1 \leq j < m \quad (5)$$

$$NGroup = NCC(VARs, \{z_j\}) \quad (6)$$

$$MinSize = MIN\_NCC(VARs, \{z_j\}) \quad (7)$$

$$MaxSize = MAX\_NCC(VARs, \{z_j\}) \quad (8)$$

$$MinDist = MIN\_NCC_C(VARs, \{z_j\}) \quad (9)$$

$$MaxDist = MAX\_NCC_C(VARs, \{z_j\}) \quad (10)$$

$$NOne = NVERTEX(VARs, \{z_j\}) \quad (11)$$

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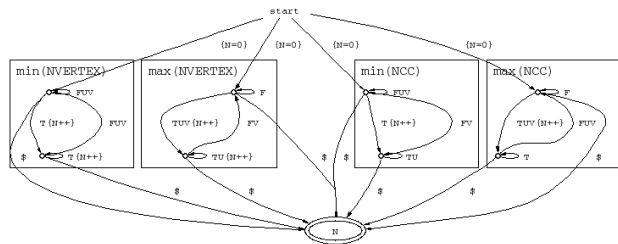
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# Bounds on graph characteristics for PATH+LOOP

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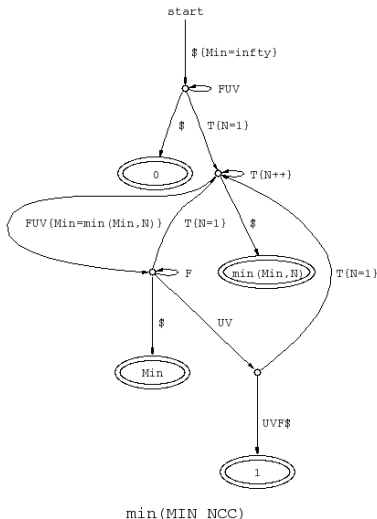
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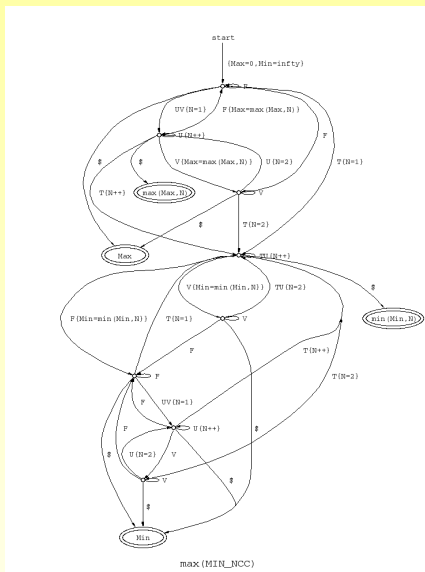
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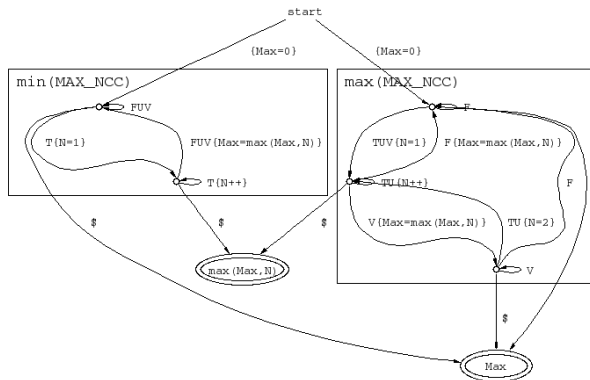
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# Some Graph-Based Filtering for PATH+LOOP

Let  $U$  be a maximal sequence of nonground vertices joined by nonzero arcs. If  $\text{dom}(\text{NCC}) = \{\underline{\text{NCC}}\}$  then:

1. Any  $U$  neighboring *two* 1-vertices is assigned to a sequence of 1s.
2. Any  $U$  neighboring *no* 1-vertex is assigned to a sequence of 0s.

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# Some Graph-Based Filtering for PATH+LOOP

Let  $U$  be a maximal sequence of nonground vertices.  
If  $\text{dom}(\text{NCC}) = \{\overline{\text{NCC}}\}$  then:

1. Within any  $U$ ,  $z_j$  are assigned to 0.
2. Any  $U$  with odd  $|U|$  neighboring *two* 1-vertices is assigned to an alternating sequence  $0, 1, \dots$
3. Any  $U$  with even  $|U|$  preceded by *one* 1-vertex is assigned to an alternating sequence  $0, 1, \dots$
4. Any  $U$  with even  $|U|$  succeeded by *one* 1-vertex is assigned to an alternating sequence  $1, 0, \dots$
5. Any  $U$  with odd  $|U|$  neighboring *no* 1-vertex is assigned to an alternating sequence  $1, 0, \dots$

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# Conclusion

- ▶ The view of Global Constraints as **Graph Properties of Structured Networks of Elementary Constraints of the Same Type** is more than just a catalog.
- ▶ Generic invariants among the non-independent graph properties for a constraint  $C$  can be looked up **automatically** and give rise to **necessary conditions**.
- ▶ Bounds on Graph Characteristics can be computed dynamically and be used for **pruning**, allowing us to get a filtering scheme from a declarative description of a global constraint.

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Towards Graph-Based F

Conclusion



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Using Graph  
Properties for Global  
Constraints for  
Necessary Conditions  
and Filtering

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Mats Carlsson,  
Jean-Xavier Rampon,  
Charlotte Truchet,  
Sophie Demassez,  
Thierry Petit



The Framework

Example: nvalue

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