

Synthesis of Search Algorithms from High-level CP Models

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Overview

- ▶ Motivation
- ▶ Introducing CP-AS
- ▶ Synthesis Process
 - ▶ Rules Library
 - ▶ Symmetry Breaking
 - ▶ Implementation
- ▶ Example Applications
- ▶ Experimental Results
- ▶ Conclusions & Future Work

Motivation

Motivation

$$\text{CP} = \text{Model} + \text{Search}$$

Motivation

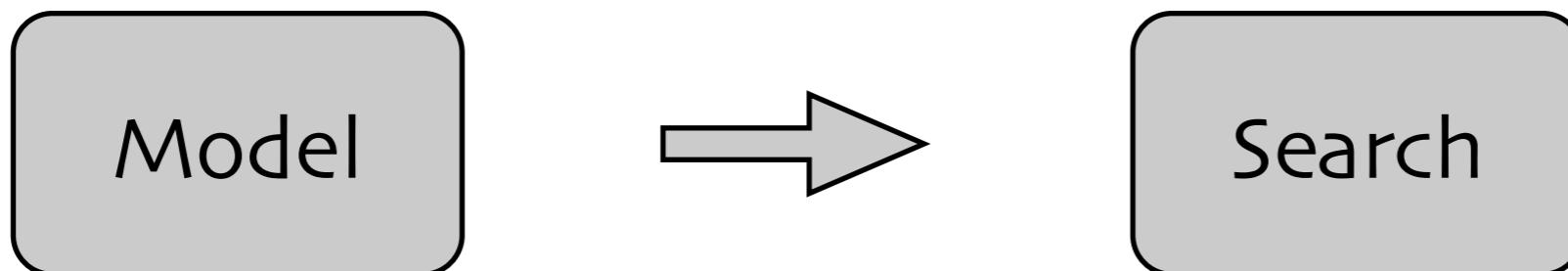
$$\text{CP} = \text{Model} + \text{Search}$$

VS.

$$x = \text{Model}$$

Motivation

- ▶ Automatic synthesis of search
- ▶ Retaining the ability to write custom search procedures
- ▶ Generate



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CP-AS

- ▶ Recognizes and classifies model structures
- ▶ Follows a rule-based approach
- ▶ Works on top of Comet



Example

```
Solver<CP> m();
minimize<m> s subject to {

    forall(i in V) m.post(c[i] <= s);
    forall(i in V, j in V : i < j)
        if (adj[i,j])
            m.post(c[i] != c[j]);

}
using {

    label(m);

}
```

Example

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    CPAS.generateSearch(m);

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```

Example

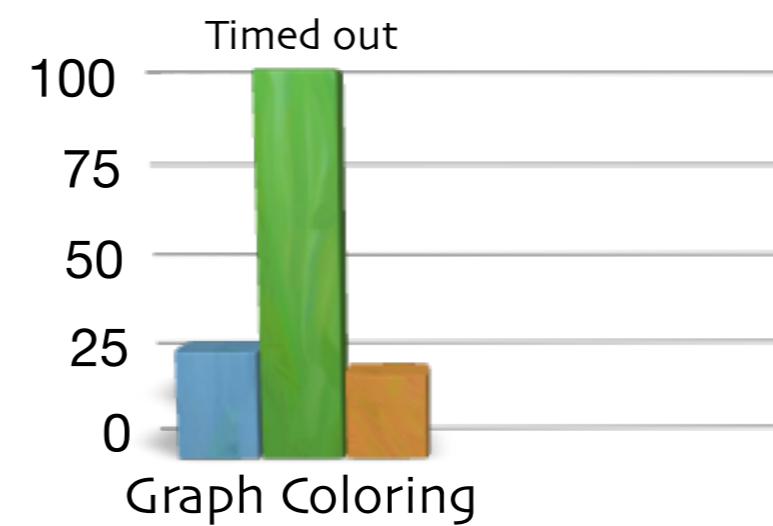
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}

using {
  CPAS.generateSearch(m);
}
  
```

- █ Synthesized Search
- █ Comet Default search
- █ Tailored Search



Related Work

- ▶ **Aeon** [Monette et al. 2009]
- ▶ **Minion** [Gent et al. 2006]
- ▶ **Algorithm Portfolio (e.g., CPHYDRA)** [O'Mahony et al. 2008]

Overview

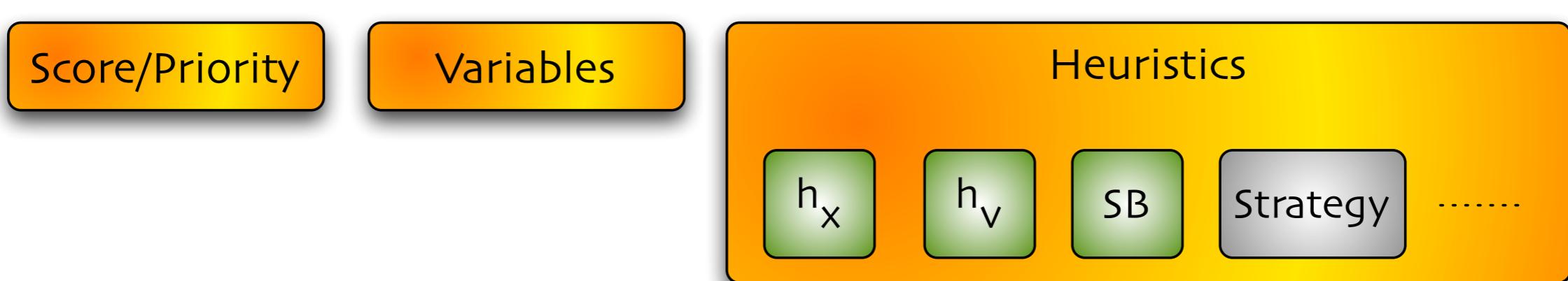
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Rules

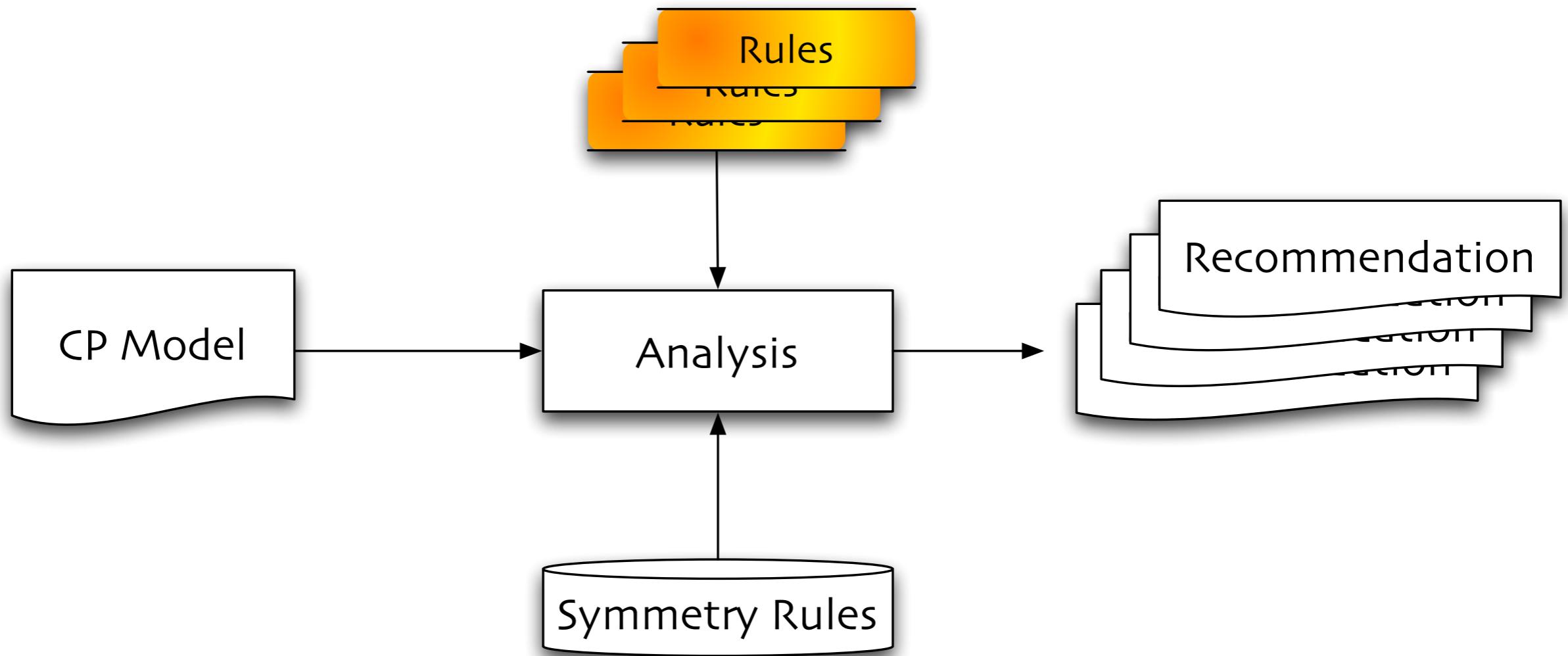
- ▶ Exploit model structures
- ▶ Generate a set of recommendations

Recommendations

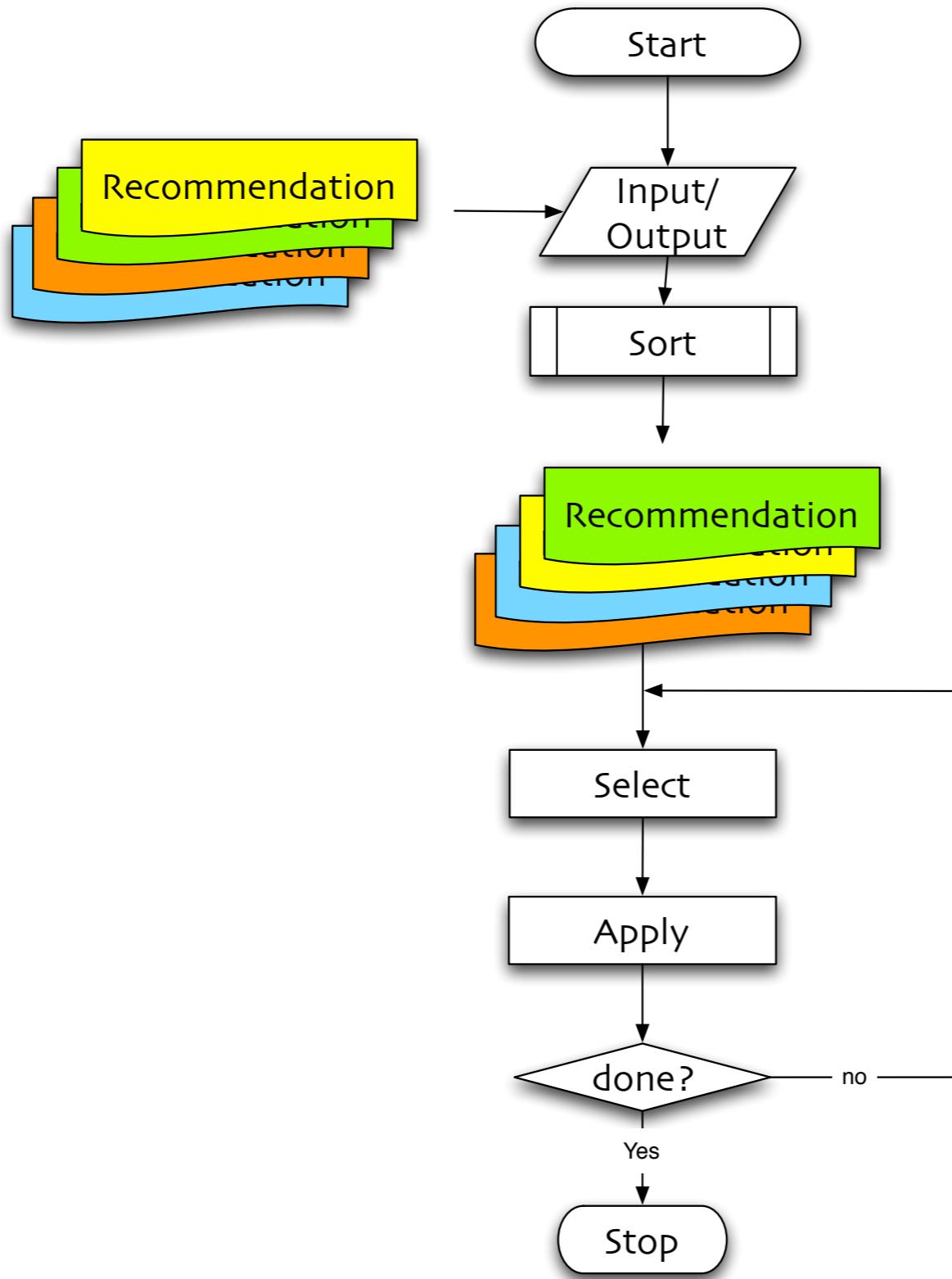
- ▶ Fully specify the search



Analysis



Search Generation



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Global Constraints Rules

- ▶ Insight
 - ▶ Capture global constraints structures
 - ▶ Currently support a subset of globals

Global Constraints Rules

► Insight

- Capture global constraints structures
- Currently support a subset of globals

AllDifferent

Knapsack

Sequence

Cardinality

Circuit

Regular

Spread

AtLeastNValue

....

Basics

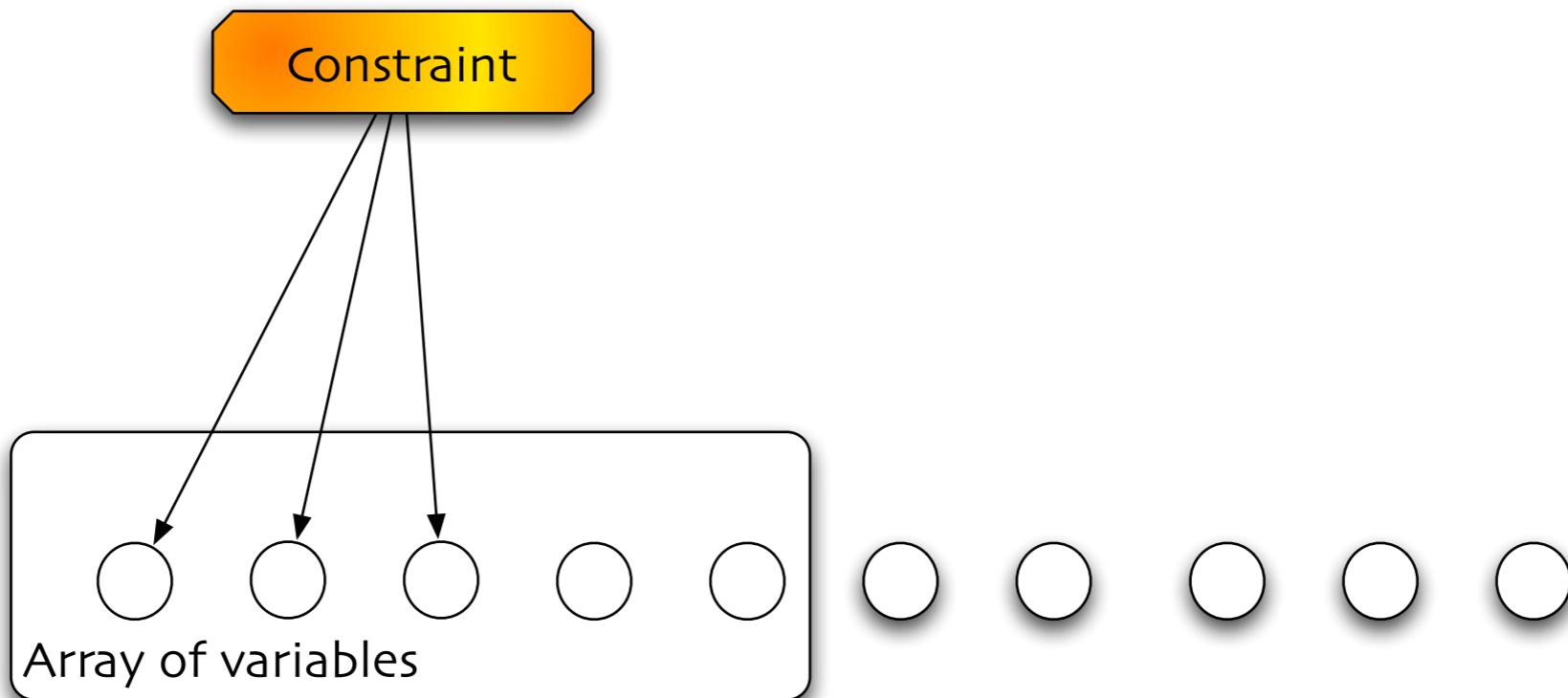
- ▶ Each global constraint (of a given type) issues one recommendation
 - ▶ Score
 - ▶ Variables affected
 - ▶ Heuristic selection

Scoring a global constraints

- ▶ Captures
 - ▶ Constraints covering
 - ▶ Constraints Homogeneity / Diversity
 - ▶ Constraints connectivity

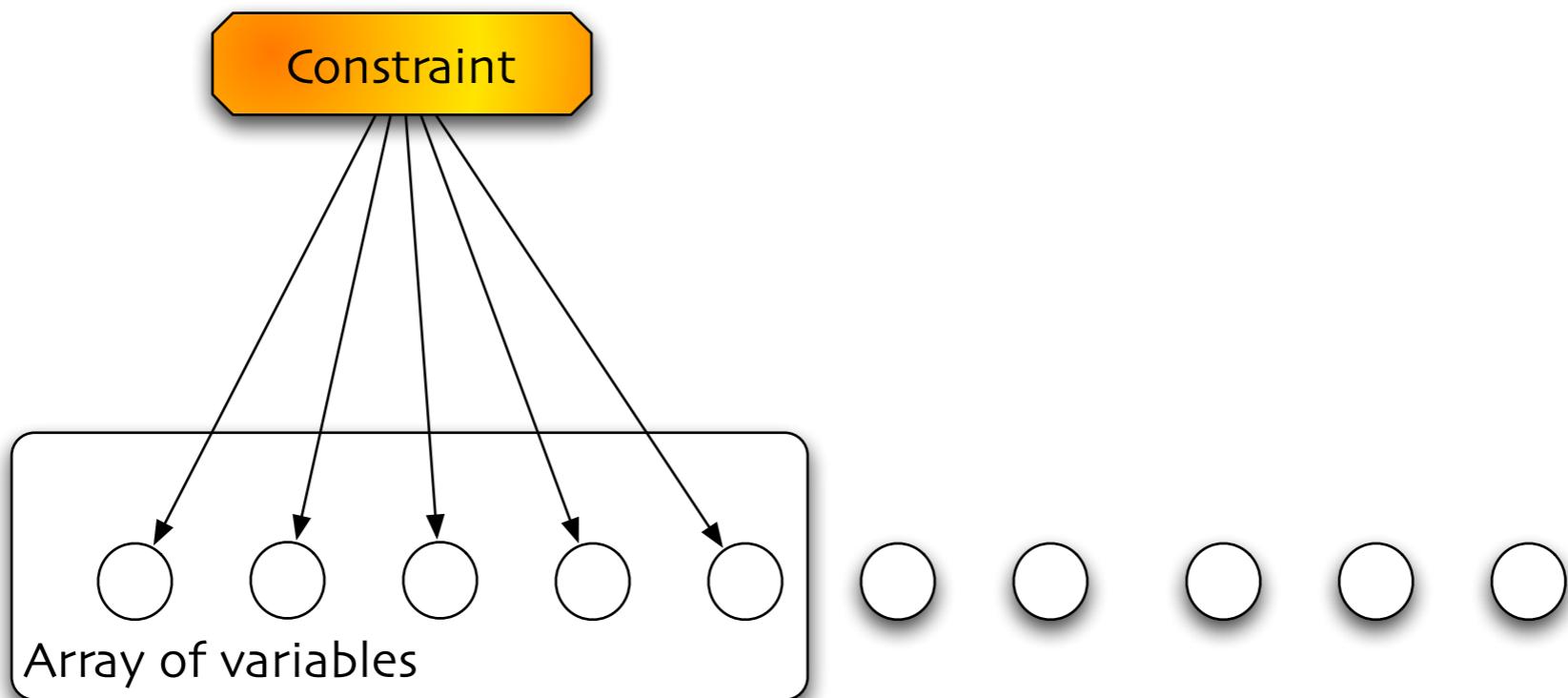
Covering

- ▶ Variable “coverage” Insight
 - ▶ Full vs. partial



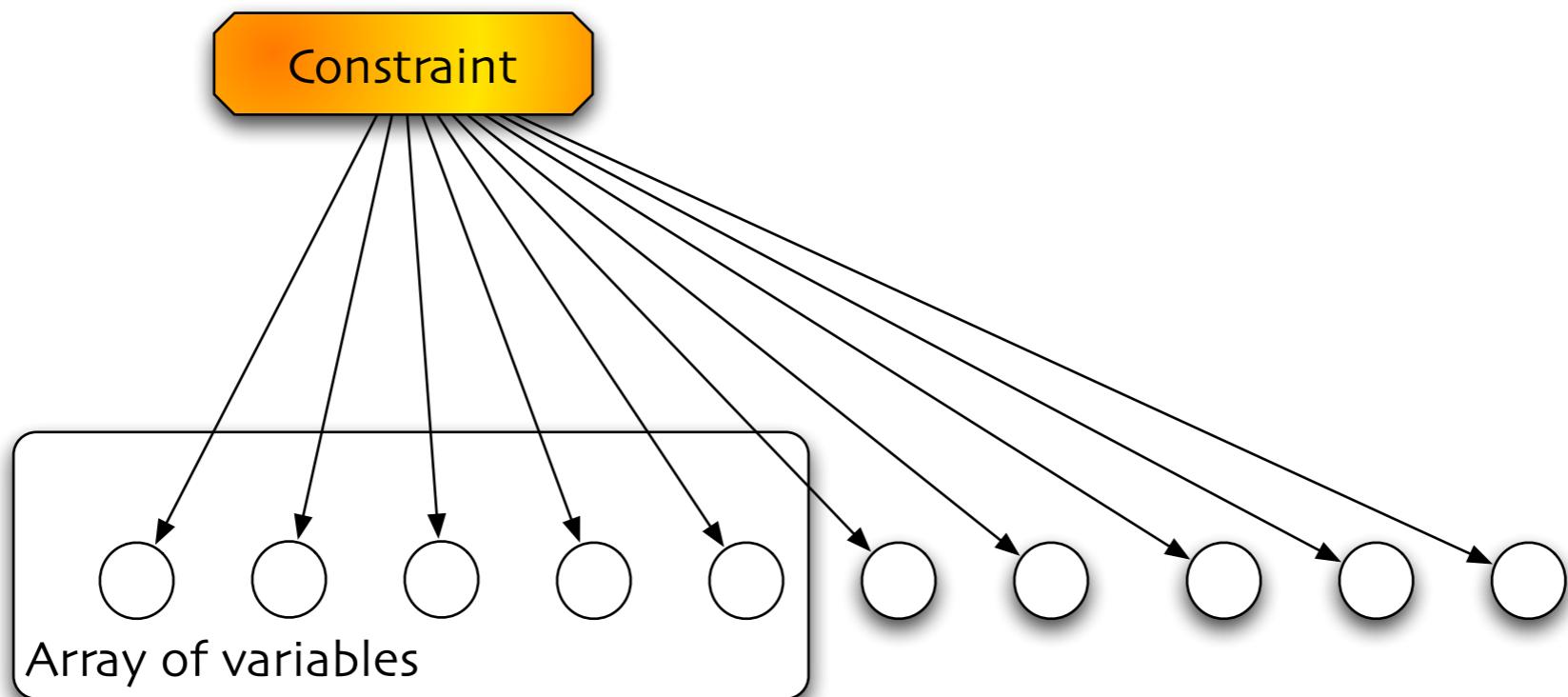
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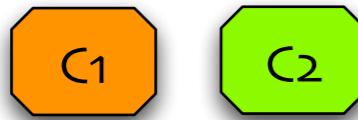
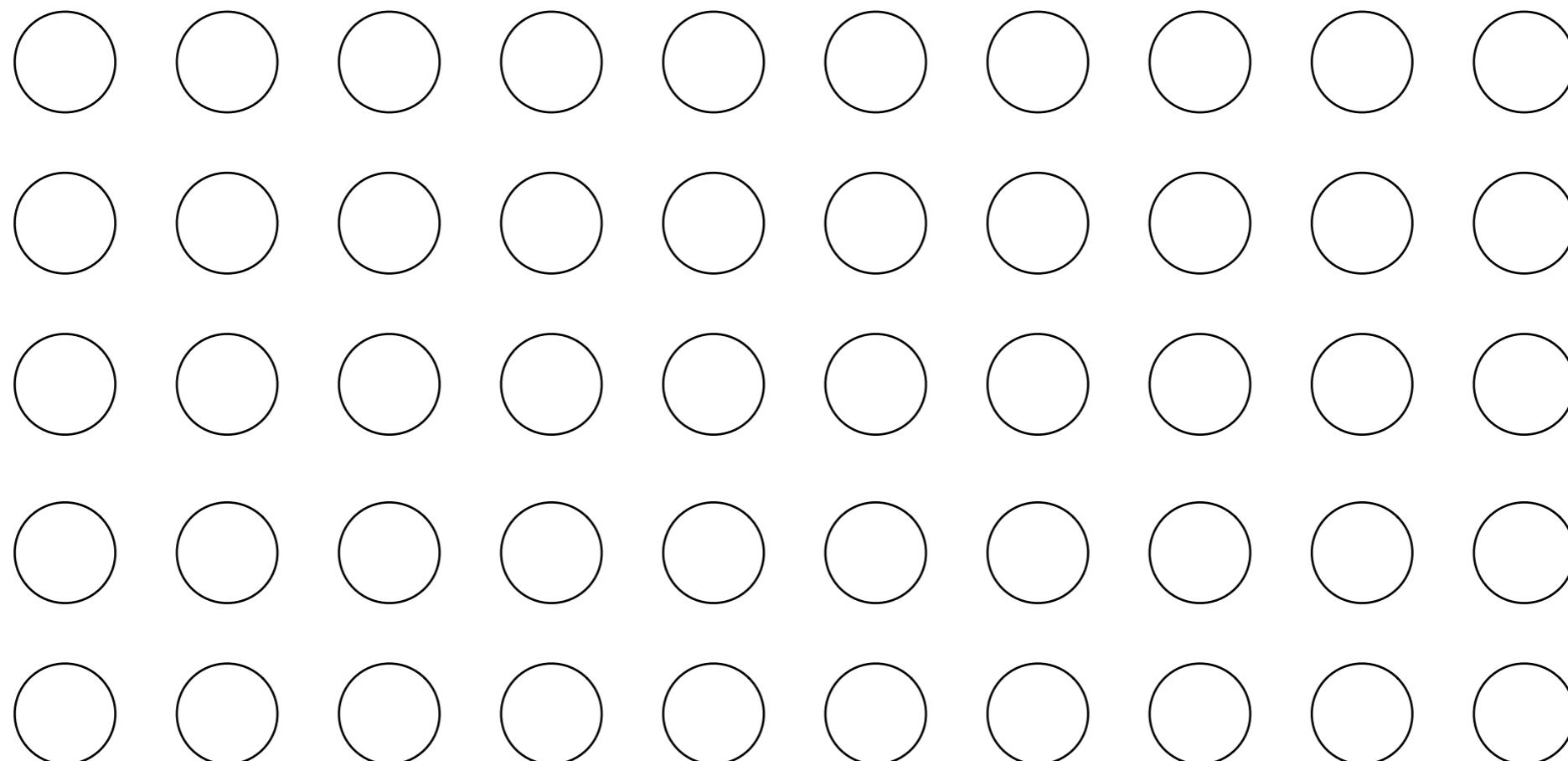
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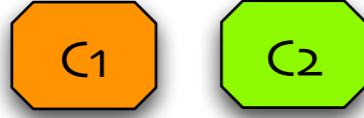
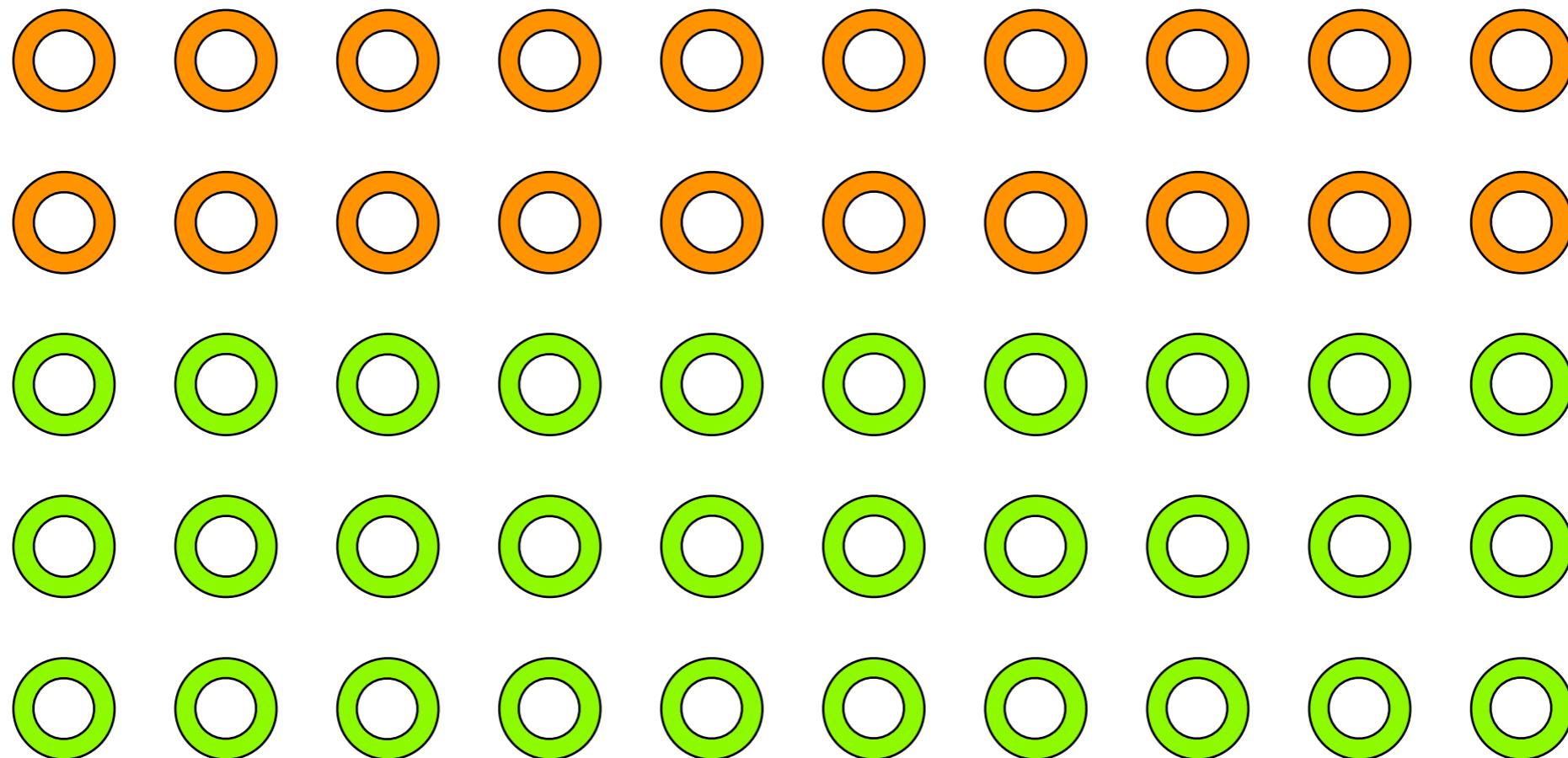
Homogeneity

► “coupling” Insight



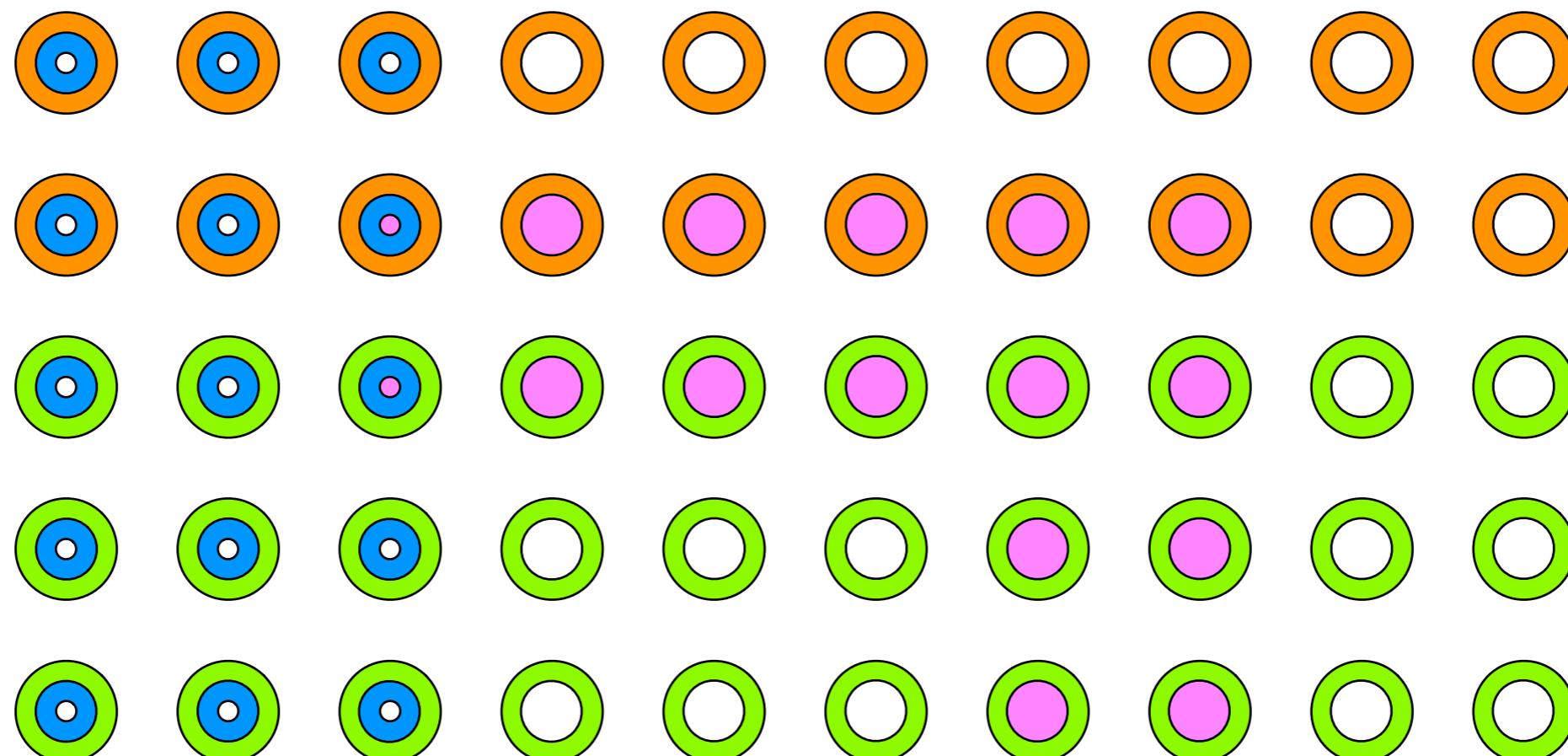
Homogeneity

► “coupling” Insight



Homogeneity

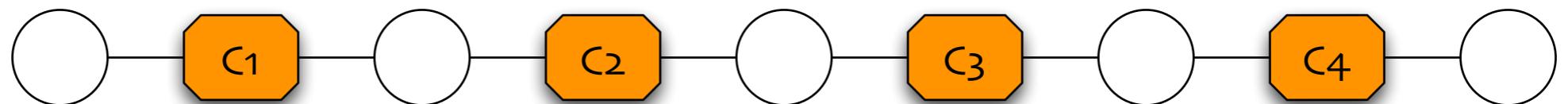
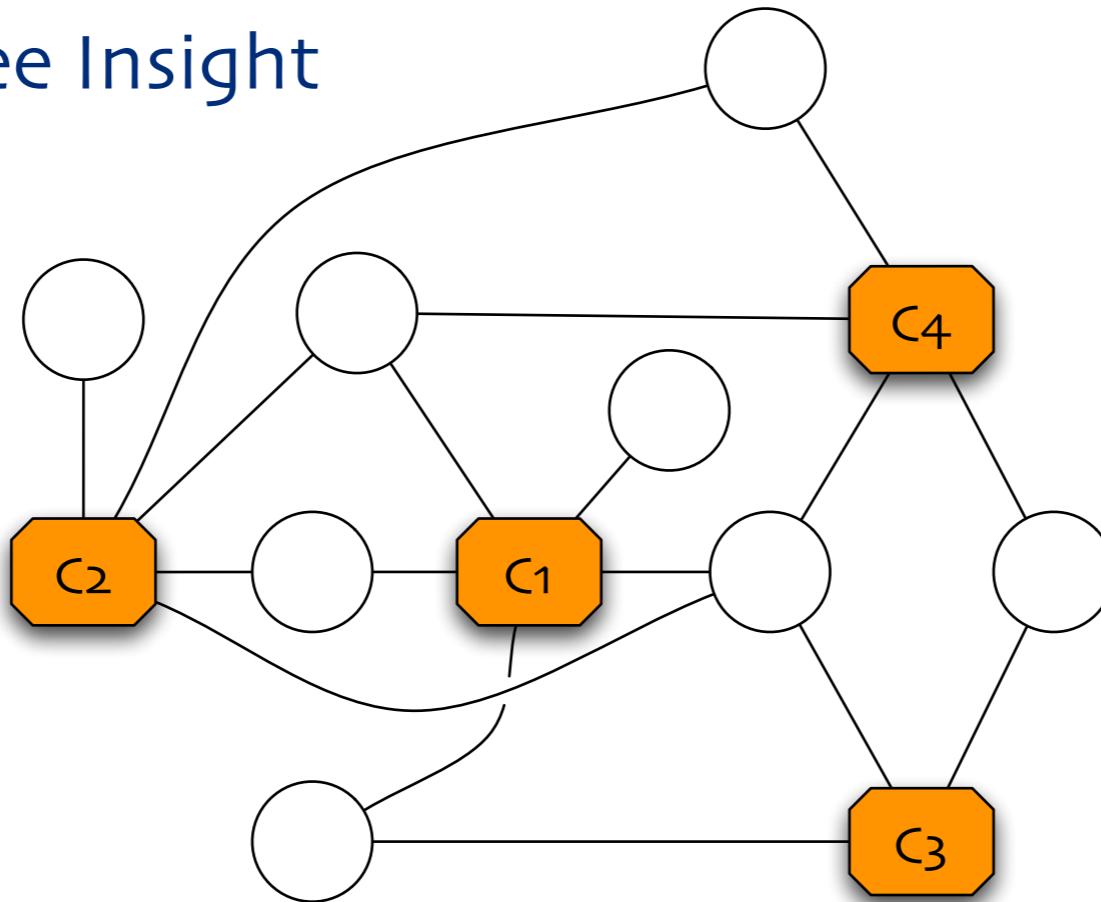
► “coupling” Insight



C_1 C_2 C_3 C_4

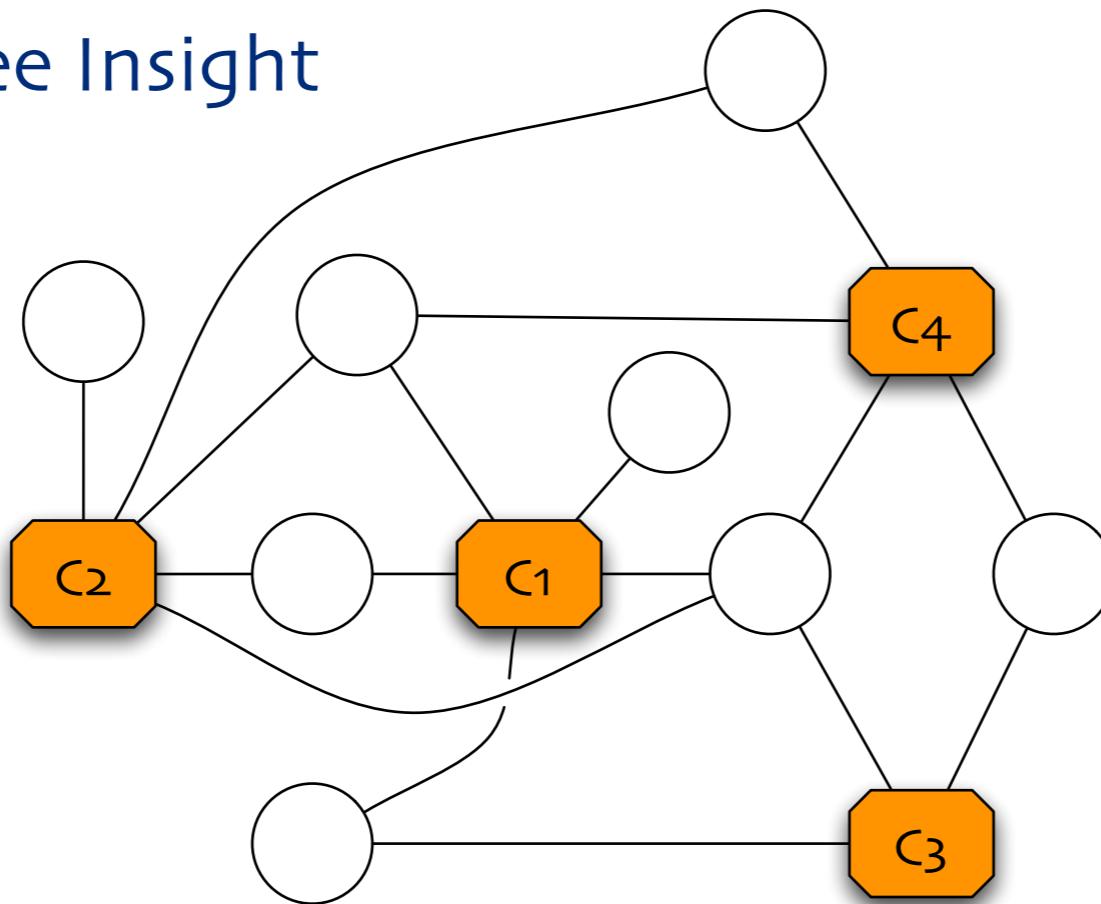
Connectivity

- ▶ Variables Degree Insight
- ▶ High vs. low

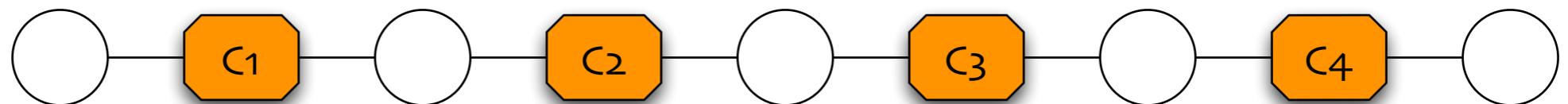


Connectivity

- ▶ Variables Degree Insight
 - ▶ High vs. low



High variables degree



Lower variables degree

Overall scoring

- ▶ Integrate three elements
 - ▶ The more uniform the constraint types, the stronger the fit
 - ▶ The higher the variables degree, the stronger the fit
 - ▶ The higher the variables coverage, the stronger the fit

$$\frac{\max_{x \in \text{vars}(c)} \deg(x)}{\max_{x \in X} \deg(x) \cdot |G(C)|}$$

If covering

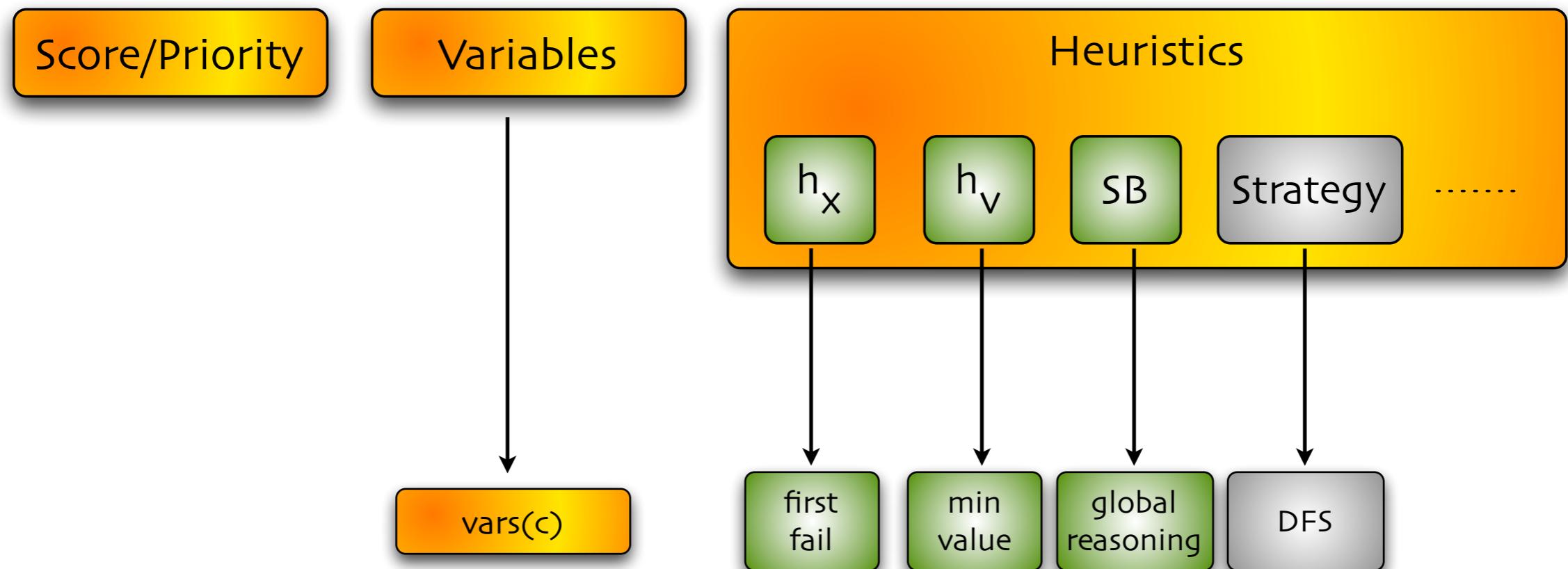
$$\frac{|\text{vars}(c)|}{\max_{k \in C : \text{type}(k) = \text{type}(c)} |\text{vars}(k)| \cdot |G(C)|}$$

Overall scoring

- ▶ Integrate three elements
 - ▶ The more uniform the constraint types, the stronger the fit
 - ▶ The higher the variables degree, the stronger the fit
 - ▶ The higher the variables coverage, the stronger the fit

score =
$$\left\{ \begin{array}{l} \frac{\max_{x \in vars(c)} deg(x)}{\max_{x \in X} deg(x) \cdot |G(C)|} \\ \\ \frac{|vars(c)|}{\max_{k \in C: type(k)=type(c)} |vars(k)| \cdot |G(C)|} \end{array} \right. \text{ If covering}$$

Global Constraints Rules

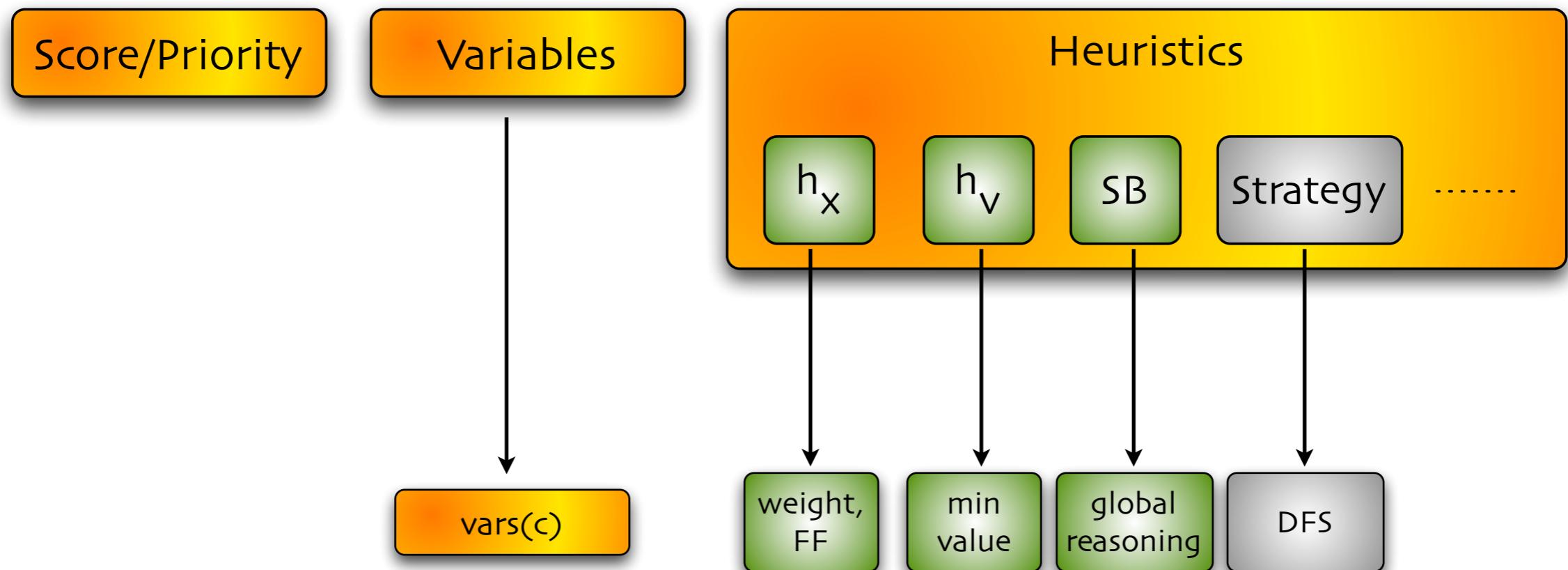


Knapsack Rule

- ▶ Full coverage of variables array
- ▶ Variable ordering by weight

$$\sum_{i \in N} w_i \cdot x_i \leq b$$

Knapsack Rule



Degree Rule

- ▶ Desirable if the static variable degrees are sufficiently diverse
- ▶ One recommendation for each model array
 - ▶ Compute relative degree frequencies (in [0..1]) $p_i = \text{freq}_i / |X|$
 - ▶ Get its score as

$$S_i = \left(1 - \sum_{i=1}^z p_i^2 \right) \cdot \frac{\max_{x \in a} \deg(x)}{\max_{x \in X} \deg(x)}$$

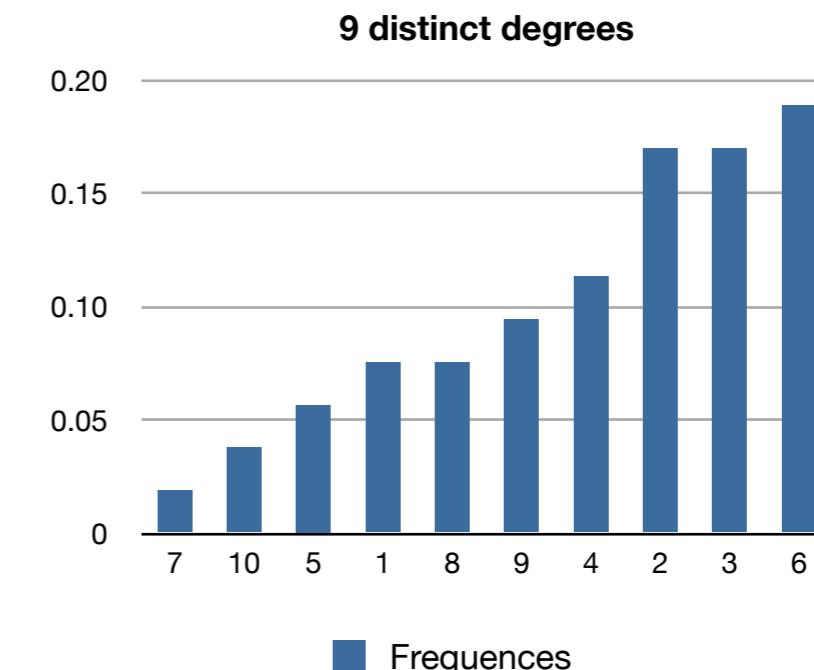
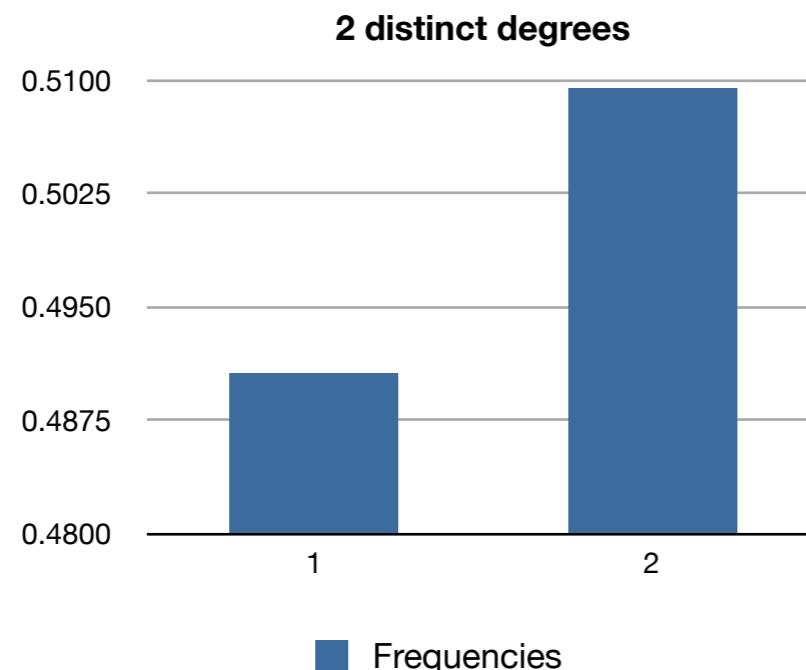
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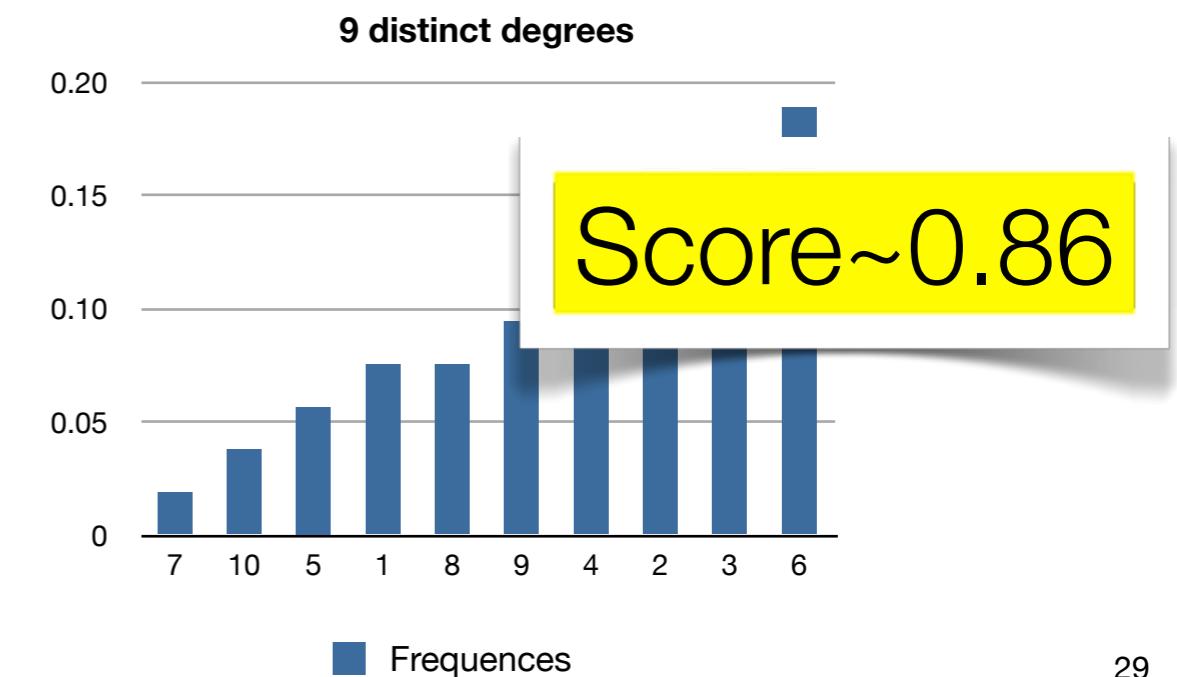
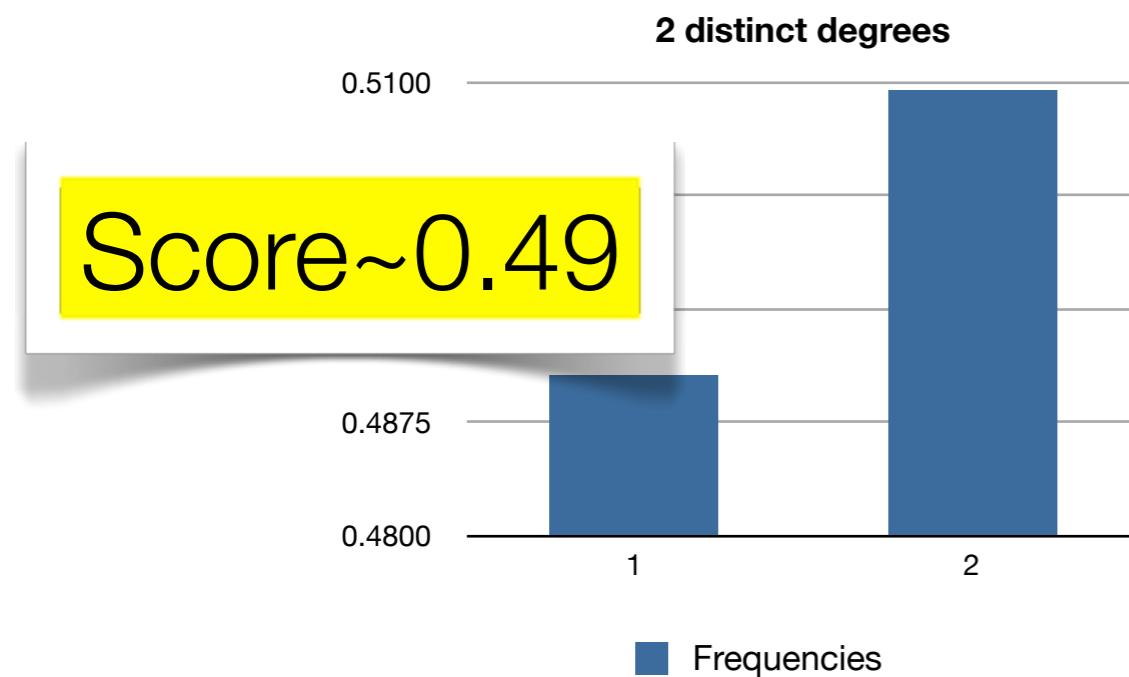
Degree Rule

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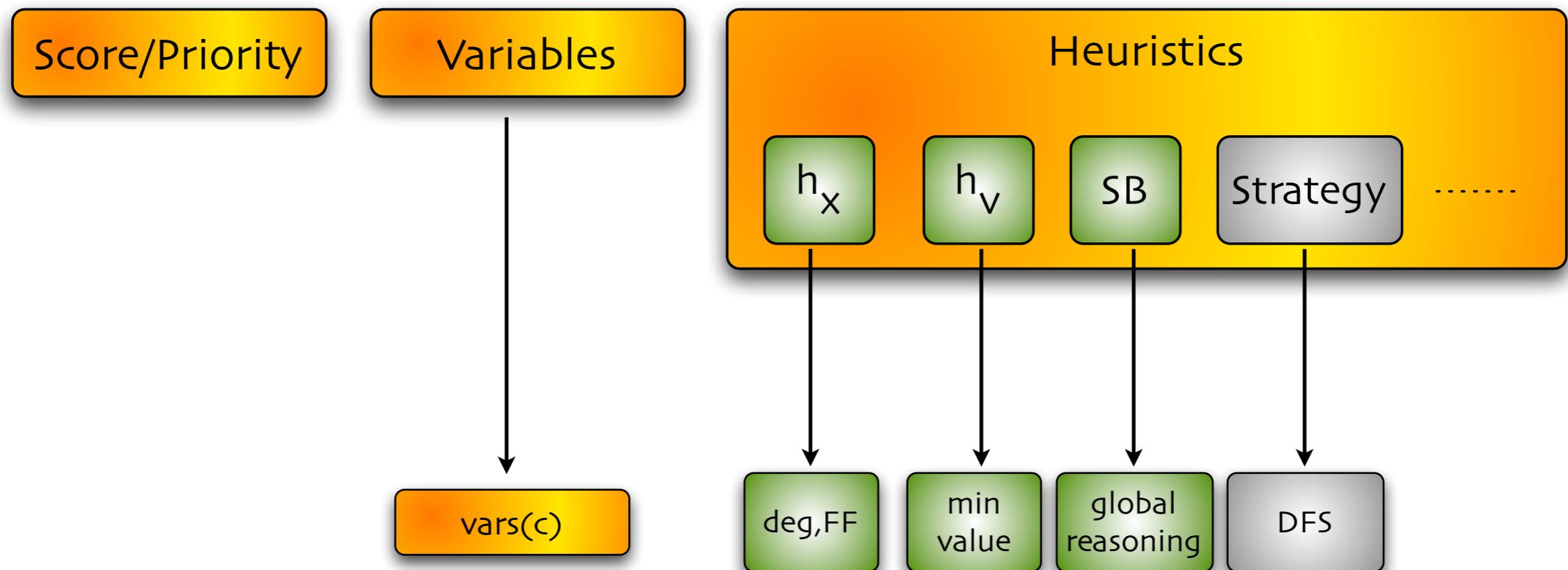
► Compute relative degree frequencies (in [0..1]) $p_i = \text{freq}_i / |X|$

► Get its score as

$$S_i = \left(1 - \sum_{i=1}^z p_i^2 \right) \cdot \frac{\max_{x \in a} \deg(x)}{\max_{x \in X} \deg(x)}$$



Degree Rule



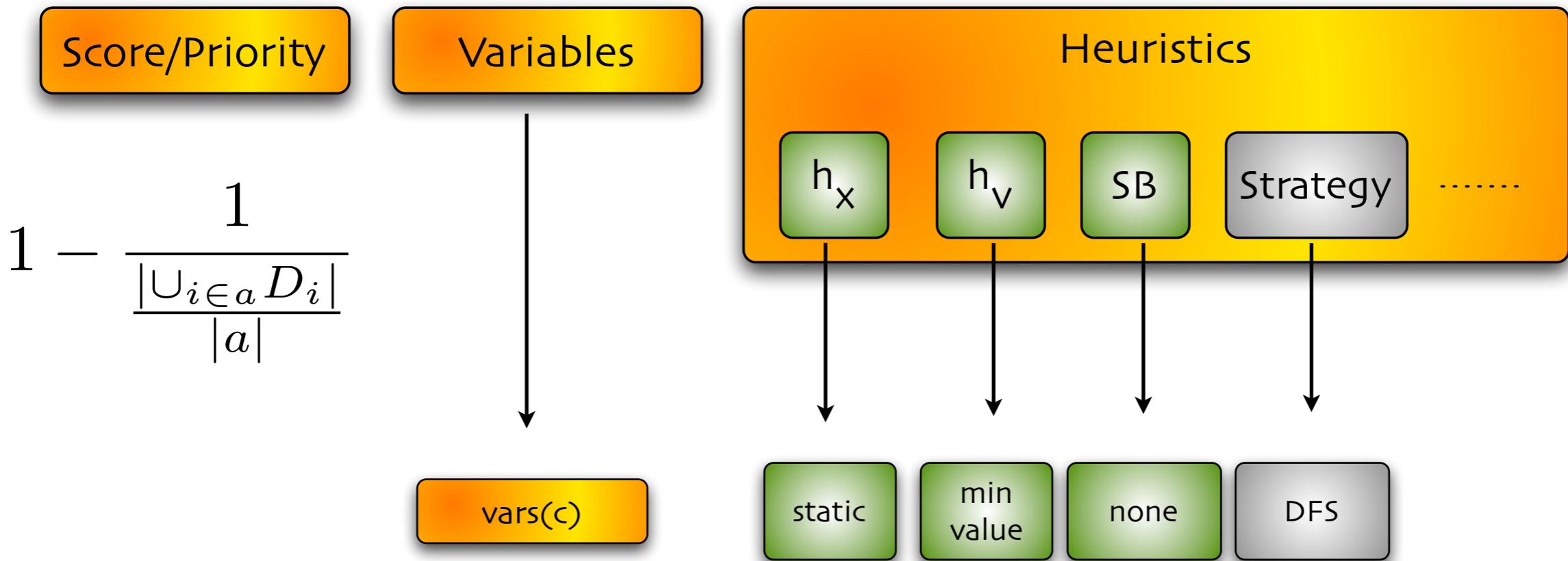
Pick Value First Rule

► Insight

- When there are far more values than variables!
- Pick a value first. Choose a variable to assign second

► Score

- Measure value density vs. array size



Most Constrained Variables Rule

- ▶ Insight
 - ▶ Variable centric rule
 - ▶ Captures the traditional static degree.

First Fail Rule

- ▶ Insight
 - ▶ Simple “default” rule
 - ▶ Used to label variables not handled by any dedicated rule

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Symmetry Breaking

- ▶ Symmetry is everywhere!
- ▶ Compositional global constraints driven approach [Van Hentenryck et al., Eriksson 2005]
- ▶ Symmetry analysis with patterns
- ▶ Once symmetry detected, go and break it!



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Mechanics

- ▶ Recommendations are composable
- ▶ Lexicographic order of score & priority
- ▶ A polymorphic method 'label'

```
forall(r in rec.getKeys()) by (-rec{r}.getScore(), rec{r}.getPriority()) {  
    rec{r}.label();  
    if (solver.isBound()) break;  
}
```



Mechanics

```
class VariableRecommendation implements Recommendation { ...
    void label() {
        var<CP>{int}[] x = getVars();
        while(!bound(x)) {
            selectMin(i in unboundVars(x))(hx(x,i)) {
                set{int} values = getValues(x[i]);
                tryall<solver>(v in values) by (hv(values,v))
                    solver.label(x[i], v);
                onFailure solver.diff(x[i], v);
            }
        }
    }
}
```

Mechanics

```
class ValueRecommendation implements Recommendation { ...
void label() {
    var<CP>{int}[] x = getVars();
    while(!bound(x)) {
        set{int} values = collect(s in x.getRange():!x[s].bound()) x[s].getMin();
        selectMin(v in values) (hv(values,v)) {
            tryall<solver>(i in unboundVars(x)) by (hx(x,i)) {
                solver.label(x[i], v);
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Benchmarks

- More than 10 models known for having non-trivial search

Progressive Party

```

Solver<CP> m();
var<CP>{int} boat[Guests,Periods](m,Hosts);
solve<m> {
    forall(g in Guests)
        m.post(allDifferent(all(p in Periods) boat[g,p]),onDomains);
    forall(p in Periods)
        m.post(multiknapsack(all(g in Guests) boat[g,p],crew,cap));
    forall(i in Guests, j in Guests : j > i)
        m.post(sum(p in Periods) (boat[i,p] == boat[j,p]) <= 1);}
CPAS.generateSearch(m);
  
```



Progressive Party

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Solver<CP> m();
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solve<m> {
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Alldifferent (0.25)

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Knapsack (0.5)

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Knapsack **(0.5)**

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Knapsack **(0.5)**

Alldifferent **(0.25)**

Alldifferent **(0.25)**

Alldifferent **(0.25)**

Alldifferent **(0.25)**

Symmetry
Breaking
OFF



Scene Allocation

```

Solver<CP> m();
var<CP>{int} shoot[Scenes](m,Days);
var<CP>{int} nbd[Actor](m,Days);
int up[i in Days] = 5;
minimize<m> sum(a in Actor) fee[a] * nbd[a]
subject to {
  forall(a in Actor)
    m.post(nbd[a]==sum(d in Days) (or(s in which[a]) shoot[s]==d));
    m.post(atmost(up,shoot),onDomains);}
CPAS.generateSearch(m);
  
```



Scene Allocation

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var<CP>{int} shoot[Scenes](m,Days);
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```

Degree **(0.15)**

Degree **(0.03)**

Cardinality **(0.10)**



Scene Allocation

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```

Degree **(0.25)**

Cardinality **(0.10)**

Degree **(0.03)**

Symmetry
Breaking
ON



Steel Slab Mill

```

Solver<CP> m();
var<CP>{int} x[Orders](m,Slabs);
var<CP>{int} l[Slabs](m,0..maxCap);
var<CP>{int} obj(m,0..nbSlabs*maxCap);
int loss[c in 0..maxCap] = min(i in Caps:capacities[i] >= c) capacities[i]-c;
minimize<m> obj subject to {
  m.post(obj == sum(s in Slabs) loss[l[s]]);
  m.post(multiknapsack(x,weight,l));
  forall(s in Slabs)
    m.post(sum(c in Colors) (or(o in colorOrders[c]) (x[o] == s)) <= 2);}
CPAS.generateSearch(m);
  
```



Steel Slab Mill

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var<CP>{int} l[Slabs](m,0..maxCap);
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  forall(s in Slabs)
    m.post(sum(c in Colors) (or(o in colorOrders[c]) (x[o] == s)) <= 2);}
CPAS.generateSearch(m);
  
```

Knapsack (1)

Degree (0.1)

Symmetry
Breaking
ON

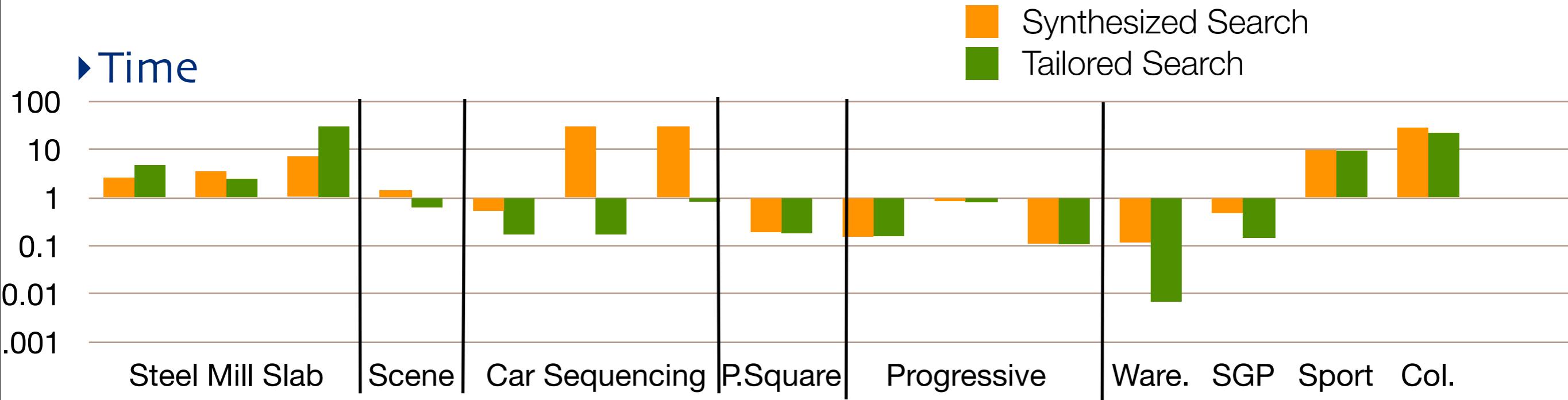


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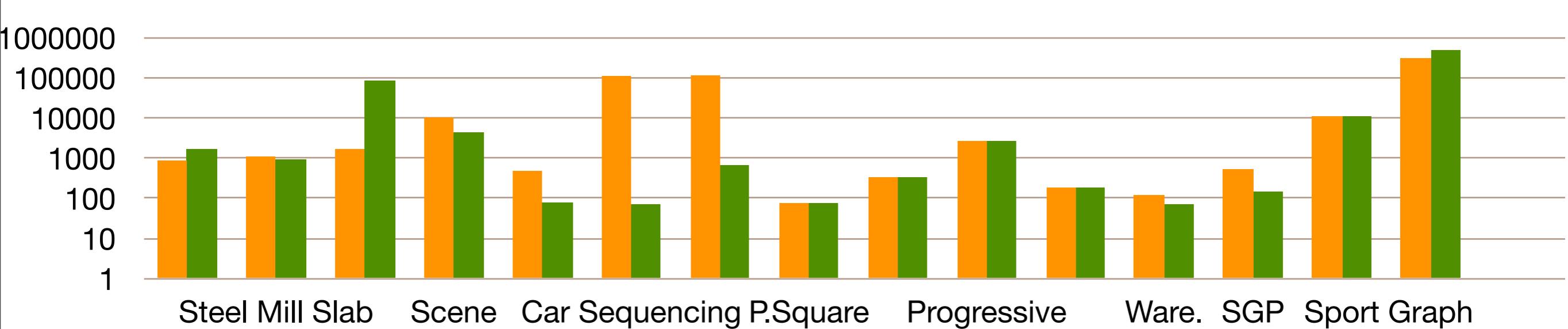
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Experimental Results

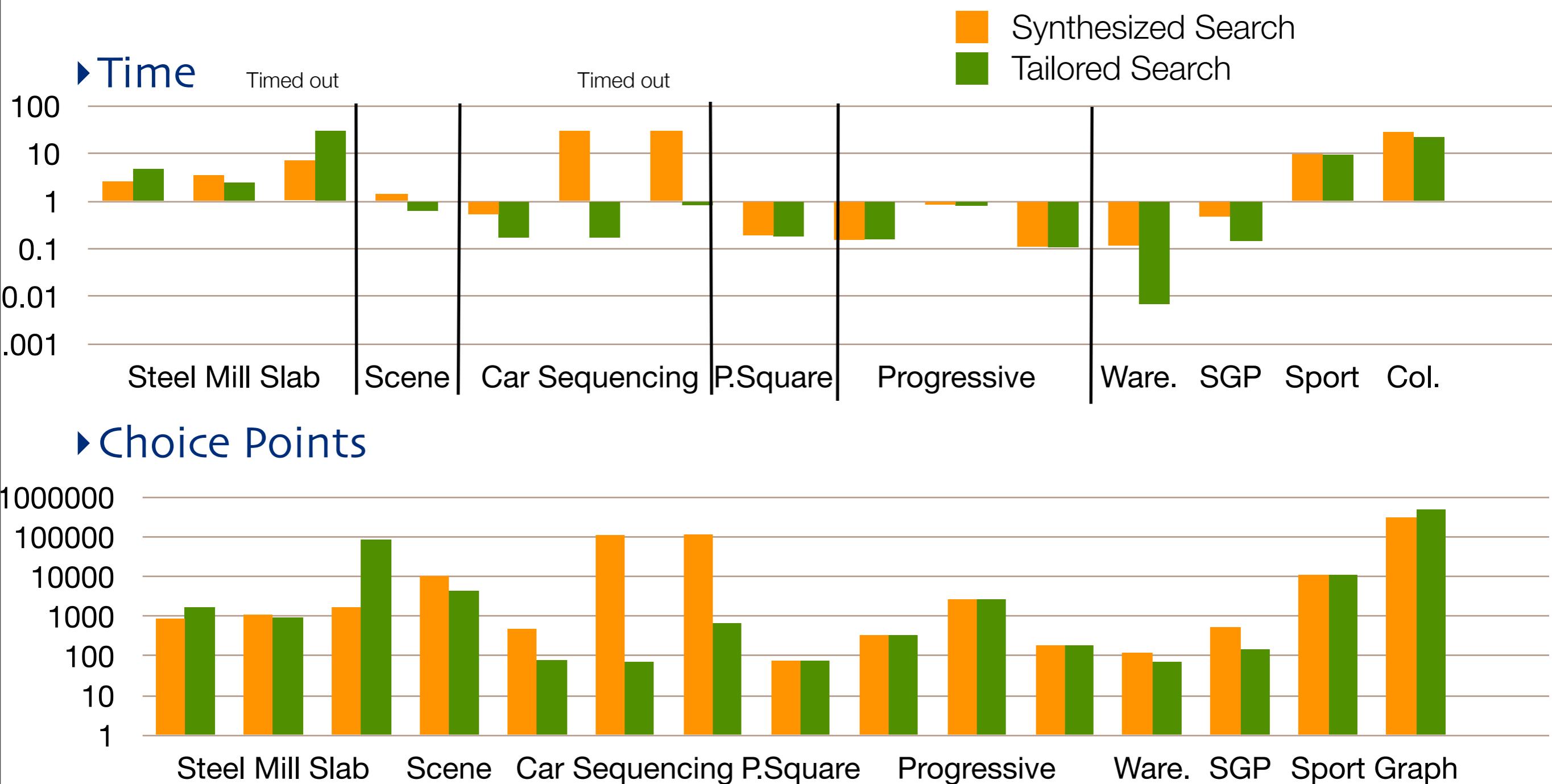
► Time



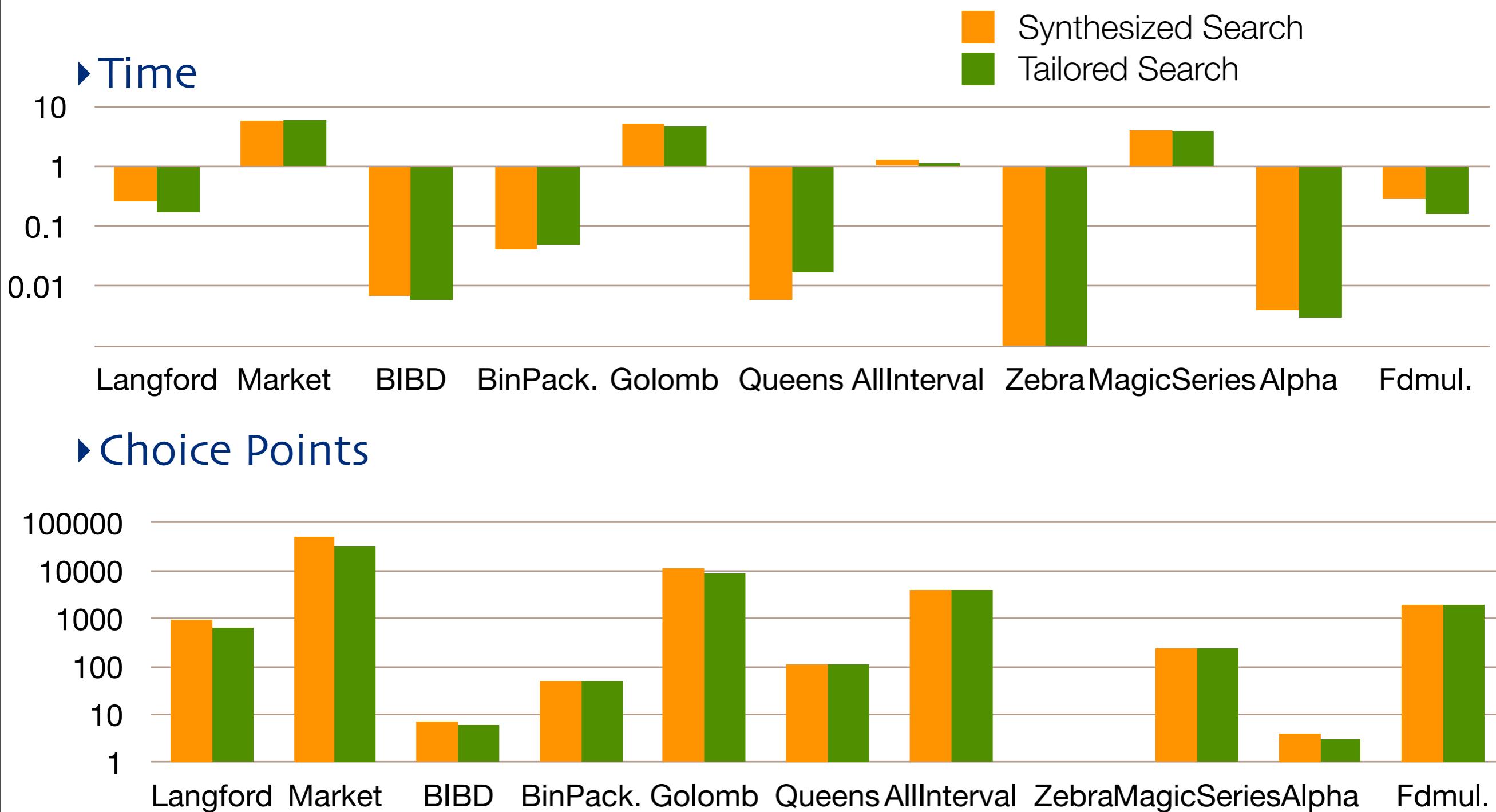
► Choice Points



Experimental Results



Experimental Results



Conclusions & Future Work

- ▶ Synthesized search is competitive
- ▶ No significant degradation in performance
- ▶ Work remains to augment the rule set
- ▶ Improvements to:
 - ▶ Composition mechanism
 - ▶ Symmetry breaking inference engine
 - ▶ Value Heuristics & Search strategies
- ▶ An in-depth empirical evaluation is absolutely essential